

FORM PTO-1449
(Rev. 7-80)U.S. DEPARTMENT OF COMMERCE
PATENT AND TRADEMARK OFFICEAtty. Docket No.
14395Serial No.
10/615,595**LIST OF PRIOR ART CITED BY APPLICANT**
(Use several sheets if necessary)APPLICANT
KHAJEPOUR et al.FILING DATE
July 9, 2003GROUP
3652

U.S. PATENT DOCUMENTS

EXAMINER R INITIAL		DOCUMENT NUMBER							DATE	NAME	CLASS	SUBCLASS	FILING DATE IF APPROPRIATE
/DU/	AA	3	2	8	6	8	5	1	11-22-1966	Sparg			
/DU/	AB	3	4	9	7	0	8	3	02-24-1970	Anderson			
/DU/	AC	3	6	3	1	7	3	7	01-04-1970	Wells			
	AD	4	6	6	6	3	6	2	05-19-1987	Landsberger et al.			
/DU/	AE	4	6	8	3	7	7	3	08-04-1987	Diamond			
	AF	4	9	7	6	5	8	2	12-11-1990	Clavel			
	AG	5	3	1	3	8	5	4	03-23-1994	Akeel			
/DU/	AH	5	3	3	3	5	1	4	08-02-1994	Toyama et al.			
/DU/	AI	5	9	6	7	7	2	9	10-19-1999	Foes			

OTHER PRIOR ART (Including Author, Title, Date, Pertinent Pages, Etc.)

/DU/	BA		"Delta, a Fast Robot with Parallel Geometry", R. Clavel, Proc. Int. Symposium on Industrial robots, April 1988, pp. 91-100.										
/DU/	BB		"Kinematics of a Three-DOF Platform with Three Extensible Limbs", Lung-Wen Tsai, Recent Advances in Robot Kinematics, pp. 401-409.										
/DU/	BC		"A Smart Kinesthetic Interactive Platform", M. Griffis et al., Advances in Robot Kinematics and Computationed Geometry, pp. 459-464.										
/DU/	BD		"Development of an Ultrahigh speed Robot FALCON using Wire Drive System", S. Kawamura et al., IEEE International Conference on Robotics and Automation 1995, pp. 215-220.										

EXAMINER

/Donald Underwood/

DATE CONSIDERED

07/03/2007

EXAMINER: Initial if reference considered, whether or not citation is in conformance with MPEP 602; Draw line through citation if not in conformance and not considered. Include copy of this form with next communication to applicant.

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